



PTAM27

Inclination sensor with robust plastic housing



- Measurement range up to $\pm 180^\circ$
- Single or dual axis measurement
- Protection class IP67
- Longitudinal water barrier; potted electronics
- Wear-free MEMS technology, shock resistant

Product versions



Analog output



Analog output, tare function



PTAM27 - Inclination sensor in MEMS technology
Version with analog output

Specifications

		Order options	
Number of axes of inclination	1 axis: Inclination in X axis 2 axes: Inclination in X and Y axes	1	1 2
Measurement range	±15 ... 180° with 1 axis or 2 axes	2	15 ... 180
Output	Voltage 0.5 ... 10 V Voltage 0.5 ... 4.5 V Voltage 0.5 ... 4.5 V Current 4 ... 20 mA, 3 wire	3	U2 U6 U8 I1
Resolution	0.1°		
Linearity	1 axis: ±0.5° (≤75°), ±1° (>75°) 2 axes: ±1° (≤75°), ±1.5° (>75°)		
Mounting	Screws M4: DIN 912, DIN 6912, DIN 7984		
Protection class	IP67		
Signal characteristics	Signal increasing CW Signal increasing CCW	4	CW CCW
Output delay	0.1 s ... 10 s / 90%	5	Tx.x
Connection	Cable, standard length 2 m Deutsch connector, not shielded	6	KAB2M
Housing material	Plastic		
Shock	DIN EN 60068-2-27:2010, 100 g/11 ms, 100 shocks		
Vibration	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles		
Temperature range	-40° ... +85°C		
Weight	approx. 20 g (without cable)		
EMC	DIN EN 61326-1:2013		

Order code

PTAM27	-	1	-	2	-	3	-	4	-	5	-	6
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Order example: PTAM27 – 1 – 90 – I1 – CW – T1.0 – KAB2M



PTAM27 - Inclination sensor in MEMS technology
Version with analog output, tare function

Specifications

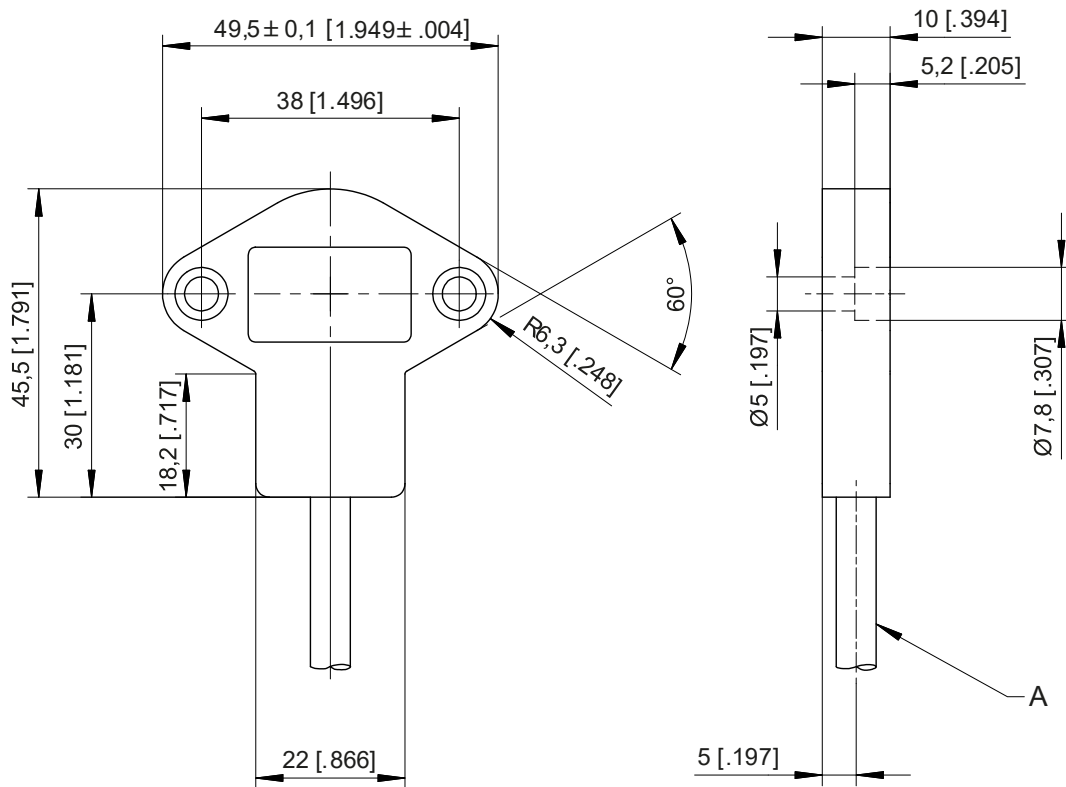
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Measurement range	±15 ... 180° with 1 axis or 2 axes	2	15 ... 180
Output	Voltage 0.5 ... 10 V, tare function Voltage 0.5 ... 4.5 V, tare function Voltage 0.5 ... 4.5 V, tare function Current 4 ... 20 mA, 3 wire, tare function	3	U2/PMZ U6/PMZ U8/PMZ I1/PMZ
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Order example: PTAM27 – 1 – 90 – I1/PMZ – CW – T1.0 – KAB2M

Dimensions



A – Cable


Dimensions in mm [inch].


Dimensions informative only.


For guaranteed dimensions consult factory.


Output specification

Analog output


U2 Voltage output 0.5 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 12 mA max. 16 mA
	Output voltage	0.5 ... 10 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 100 \times 10^{-6}$ / °C f.s. (typical)
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013


U6 Voltage output 0.5 ... 4.5 V 	Excitation voltage	5 V DC ± 10 %
	Excitation current	typical 13 mA max. 16 mA
	Output voltage	10 ... 90 % of the excitation voltage
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 100 \times 10^{-6}$ / °C f.s. (typical)
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013


U8 Voltage output 0.5 ... 4,5 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 12 mA max. 16 mA
	Output voltage	0.5 ... 4,5 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 100 \times 10^{-6}$ / °C f.s. (typical)
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013


I1 Current output 4 ... 20 mA, 3 wires 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 32 mA max. 36 mA
	Load R _L	500 Ω max.
	Output current	4 ... 20 mA
	Measuring rate	1 kHz standard
	Stability (temperature)	±100 x 10 ⁻⁶ / °C f.s. (typical)
	Protection	Reverse polarity, short circuit
	Operating temperature	-40 ... +85 °C
	EMC	DIN EN 61326-1:2013

Analog output, tare function

U2/PMZ Voltage output 0.5 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 12 mA max. 16 mA
	Output voltage	0.5 ... 10 V DC
	Output current	2 mA max.
	Measuring rate	1 kHz standard
	Stability (temperature)	$\pm 100 \times 10^{-6}$ / °C f.s. (typical)
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Tare function ZERO (PMZ)

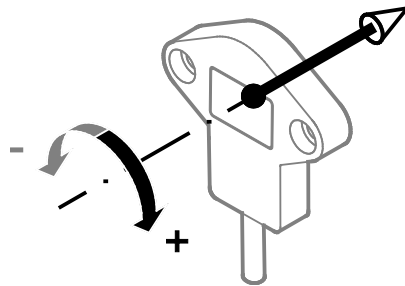
Programming the zero point by the customer:

The tare function "ZERO" allows to program the zero point of the output range by using a signal ZERO available at the connector. This Signal ZERO must be connected with GND via a push button. At first the sensor must be brought into the zero position. Pushing the button for 2 seconds sets the actual position as the zero point. The values are available as well after switching off the sensor.

Position of the inclination axis and characteristic of the linear output PTxM27

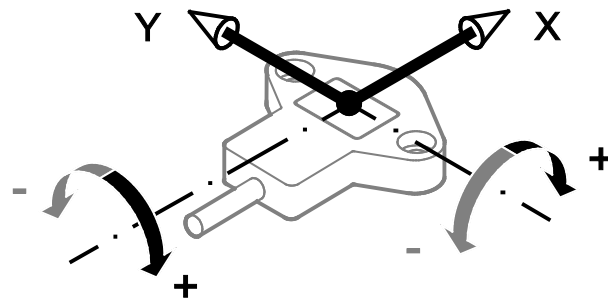
PTxM27

1 axis



PTxM27

2 axes



Output signal

