



## PCFP25

Displacement sensor in ultra flat profile for tight mounting spaces



- Protection class up to IP67
- Ultra flat profile housing: only 8 mm high
- Wear and maintenance free
- High level of shock resistance up to 50 g (100 shocks)
- Guiding distance of up to 19 mm (depending on magnet/profile)

### Product versions



Analog output, 1 channel



Analog output, 2 channels



Digital output SSI



Digital output CANopen





1) VZx.x = velocity with direction detection (with 1 magnet only), in steps of 0.1 m/s

<b>Example: VZ1.5</b>	towards start position		towards end position
	-1.5 m/s	0	1.5 m/s
Output U2:	0.5 V	5.25 V	10 V
Output I1:	4 mA	12 mA	20 mA

2) VAx.x = velocity without direction detection (with 1 magnet only), in steps of 0.1 m/s

<b>Example: VA1.5</b>	towards start position		towards end position
	-1.5 m/s	0	1.5 m/s
Output U2:	10 V	0.5 V	10 V
Output I1:	20 mA	4 mA	20 mA

**Accessories:**

**Position magnets (see page 12)**

**Mounting sets (see page 9)**



PCFP25 - Magnetostrictive Position Sensor in ultra flat profile  
Version with digital output SSI

Specifications

			Order options
Measurement range	100 ... 5750 (in 10 mm increments) other lengths upon request	<b>1</b>	100 ... 5750
Resolution	5 / 10 / 20 / 50 / 100 µm	<b>2</b>	5 / 10 / 20 / 50 / 100
Output	Synchronous serial interface (SSI)	<b>3</b>	SSI
Output code	Gray Dual	<b>4</b>	G D
Number of data bits	24 bit 25 bit	<b>5</b>	24 25
Sampling rate	Up to 1 kHz, depending on the measurement range		
Linearity	Ranges >500 mm: ±0.10 % f.s. ±0.02 % f.s. Ranges ≤500 mm: ±0.5 mm ±0.2 mm	<b>6</b>	L10 L02 L10 L02MM
Repeatability	±3 µm		
Housing material	AlMgSi1 and plastic		
Protection class	IP64 (optional IP67)		
Mounting	Mounting set PCFP25-BFS1		
Connection	Cable, standard length 2 m	<b>7</b>	KAB2M
Temperature range	-40 ... +85°C		
Shock	DIN EN 60068-2-27:2010, 50 g/11 ms, 100 shocks		
Vibration	DIN EN 60068-2-6:2008, 20 g 10 Hz-2 kHz, 10 cycles		
EMC	DIN EN 61326-1:2013		

Order code

PCFP25	-	<b>1</b>	-	<b>2</b>	-	<b>3</b>	/	<b>4</b>	/	<b>5</b>	-	<b>6</b>	-	<b>7</b>
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Order example: PCFP25 – 1000 – 5 – SSI / G / 24 – L10 – KAB2M

Accessories:

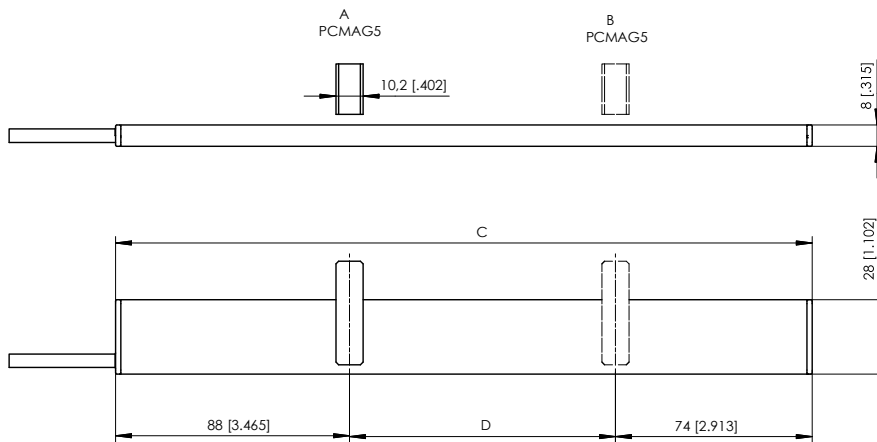
Position magnets (see page 12)

Mounting sets (see page 9)



## Dimensions

### Cable output



A – Start position

B – End position

C – Total length = Measurement length + 162 [6.378] (e.g. 262 [10.315])

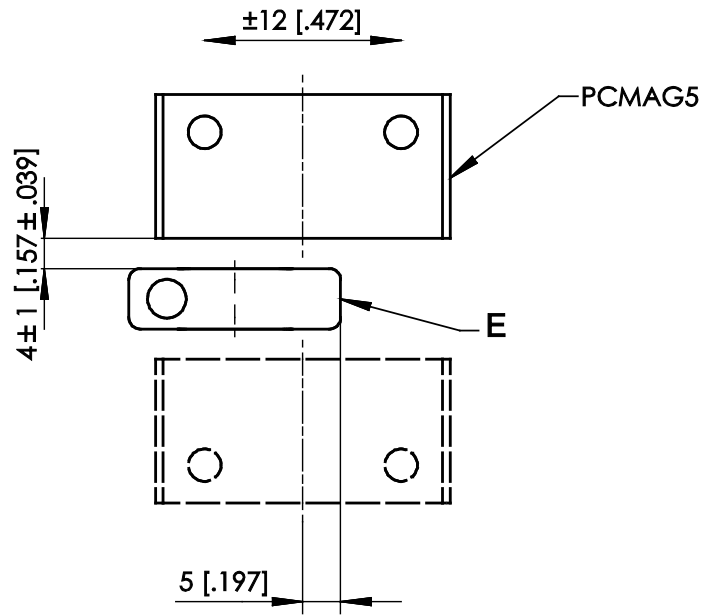
D – Measurement length (e.g. 100 [3.937])

Dimensions in mm [inch]

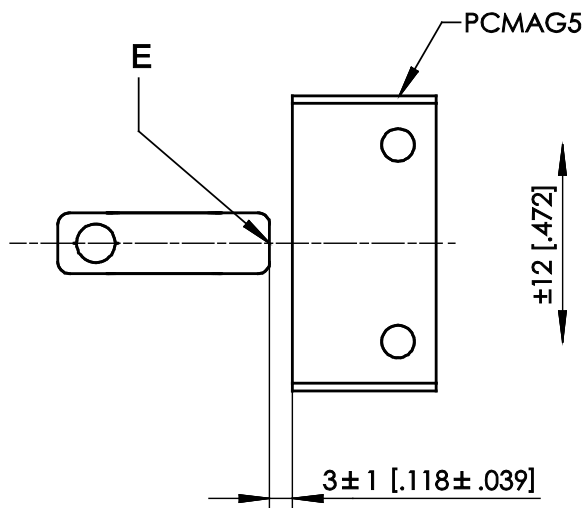
Dimensions informative only.

For guaranteed dimensions consult factory.

Magnet positions



Alternative magnet positions

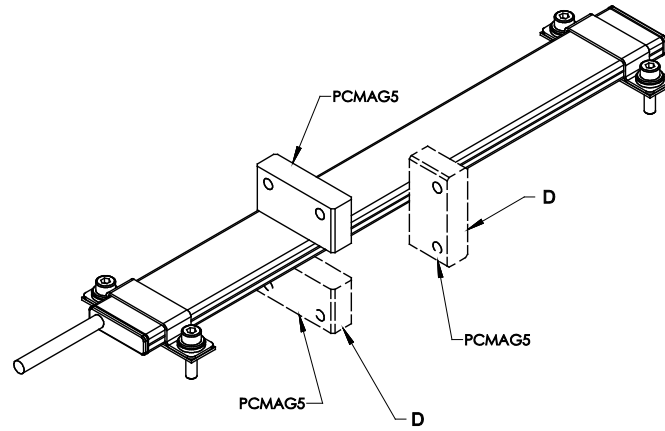


E - Marking

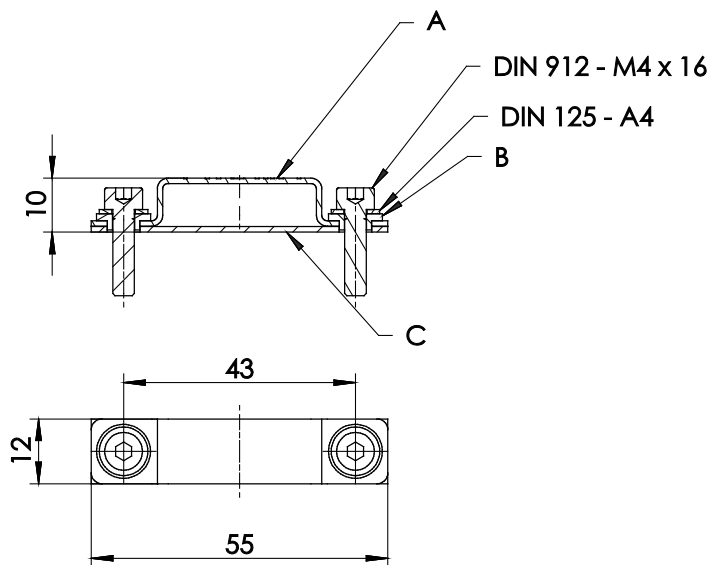


## Mounting sets

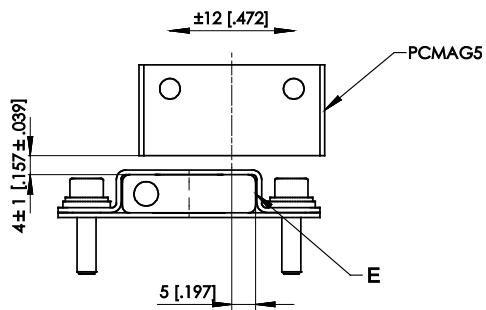
### Mounting set PCFP25-BFS1



D – Alternative magnet position



A – Mounting clamp  
B – Isolation sleeve  
C – Isolation strip

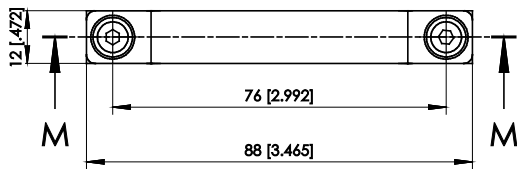
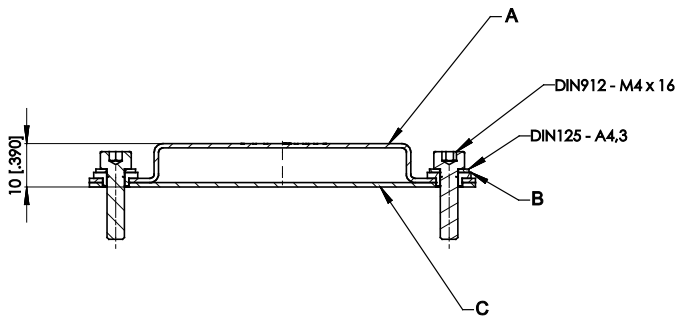
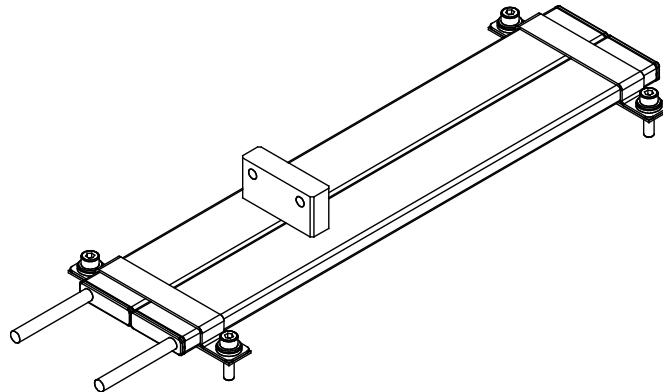


E - Marking

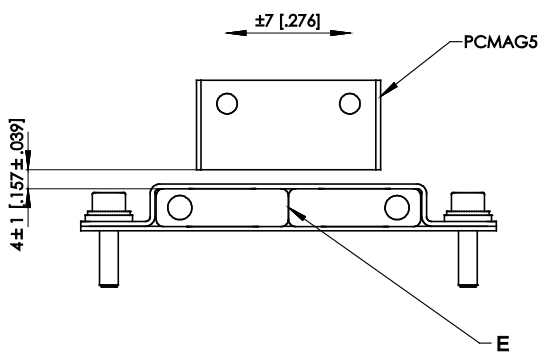
Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions consult factory.

Mounting set PCFP25-RF-BFS1

Redundant version  
Horizontal  
arrangement



A – Mounting clamp  
B – Isolation sleeve  
C – Isolation strip

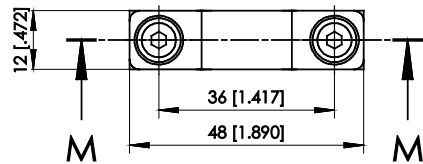
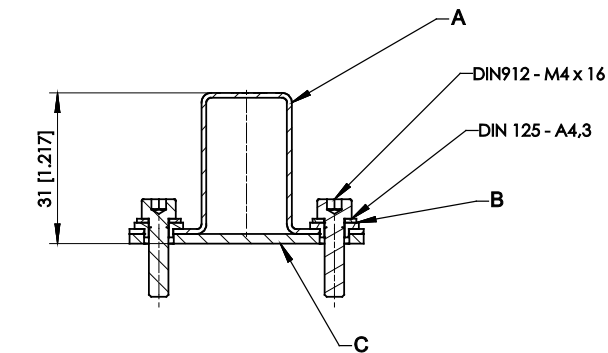
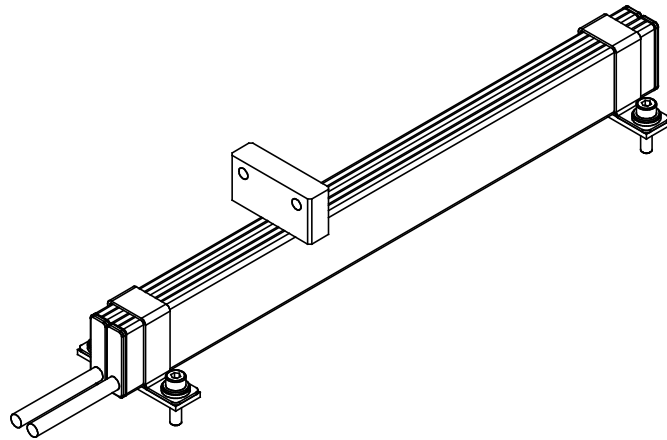


E – Marking

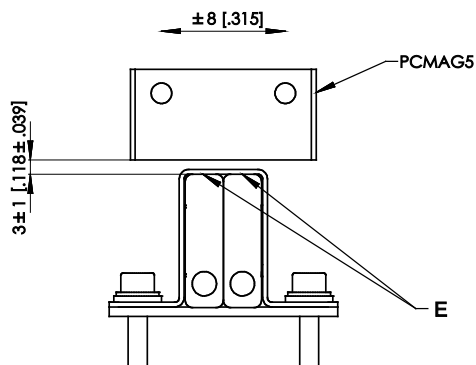
Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions consult factory.

Mounting set PCFP25-RH-BFS1

Redundant version  
Vertical arrangement



A – Mounting clamp  
B – Isolation sleeve  
C – Isolation strip



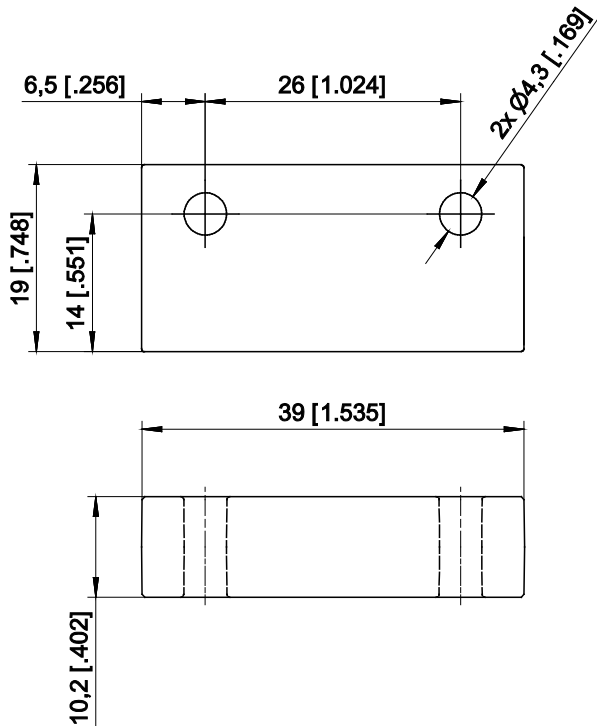
E – Marking

Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions consult factory.

## Magnets

PCMAG5


Standard magnet





Dimensions in mm [inch]  
Dimensions informative only.  
For guaranteed dimensions consult factory.


## Output specification

### Analog output

<b>U1</b> Voltage output 0 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 23 mA at 24 V DC typical 46 mA at 12 V DC max. 80 mA
	Output voltage	0 ... 10 V DC
	Output current	2 mA max.
	Output load	>5kΩ
	Resolution	16 bit f.s. min. 10 μm
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0,5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85°C
	EMC	DIN EN 61326-1:2013

<b>U2</b> Voltage output 0,5 ... 10 V 	Excitation voltage	18 ... 36 V DC
	Excitation current	typical 23 mA at 24 V DC typical 46 mA at 12 V DC max. 80 mA
	Output voltage	0,5 ... 10 V DC
	Output current	2 mA max.
	Output load	>5kΩ
	Resolution	16 bit f.s., min. 10 μm
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0,5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85°C
	EMC	DIN EN 61326-1:2013

<b>U8</b> Voltage output 0.5 ... 4.5 V 	Excitation voltage	10 ... 36 V DC
	Excitation current	typical 23 at 24 V DC typical 46 mA at 12 V DC max. 80 mA
	Output voltage	0.5 ... 4.5 V DC
	Output current	2 mA max.
	Output load	>5kΩ
	Resolution	16 bit f.s., min. 10 μm
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0,5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85°C
	EMC	DIN EN 61326-1:2013

<b>I1</b> Current output 4 ... 20 mA, 3 wire 	Excitation voltage	18 ... 36 V DC (10 ... 36 V for R <sub>L</sub> ≤ 250Ω)
	Excitation current	Typical 36 mA at 24 V DC Typical 66 mA at 12 V DC 100 mA max.
	Load resistor R <sub>L</sub>	350 Ω max.
	Output current	4 ... 20 mA (max. 30 mA at failure)
	Resolution	16 bit f.s. min. 10 μm
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Protection	Reverse polarity, short circuit
	Output noise	0,5 mV <sub>RMS</sub>
	Operating temperature	-40 ... +85°C
	EMC	DIN EN 61326-1:2013

## Diagnostic on analog outputs

### Behaviour of the analog signal output in case of error

In case of error (magnet missing or outside the measuring range) the analog output signal will assume a state according to the following options:

#### Alarm\_HIGH

The output voltage resp. the output current is at HIGH level (overrange).

#### Alarm\_LOW

The output voltage resp. the output current is at LOW level (underrange).

#### Alarm\_HOLD

The output voltage resp. the output current will keep the last valid state.

	<b>Alarm_HIGH</b> (Standard)	<b>Alarm_LOW</b> (.../U)	<b>Alarm_HOLD</b> (.../H)
<b>U1</b>	$U_{out} \geq 10.5 \text{ V}$	—	keeps last valid state (Order code <b>U1/H</b> )
<b>U2</b>	$U_{out} \geq 10.5 \text{ V}$	$U_{out} < 0.25 \text{ V}$ (Order code <b>U2/U</b> )	keeps last valid state (Order code <b>U2/H</b> )
<b>U8</b>	$U_{out} \geq 10 \text{ V}$	$U_{out} < 0,25 \text{ V}$ (Order code <b>U8/U</b> )	keeps last valid state (Order code <b>U8/H</b> )
<b>I1</b>	$I_{out} \geq 21 \text{ mA}$	$1.5 \dots 2 \text{ mA}$ (Order code <b>I1/U</b> )	keeps last valid state (Order code <b>I1/H</b> )

### Error signal for SSI output

If the sensor cannot detect a magnet, the position value will take the maximum value (0xFFFFF) for 24 bits and (0x1FFFFFF) for 25 bits.


### Option - PMU for analog output U1, U2, U8 and I1

#### Programming of the start and end value by the customer:

The option PMU allows to program the start value and the end value of the output range by a programming signal SPAN/ZERO available at the connector. This Signal SPAN/ZERO must be connected with GND via a push button, then position magnet of the sensor must be moved to the start resp. end position. Pushing the button between 2 and 4 seconds sets the actual position as start position, pushing the button more than 5 seconds sets the actual position as end position. The values will be stored and are available after switching off the sensor.

To reset the sensor to the factory values the button must be pushed for longer than two seconds when the sensor is switched on.

### Digital output

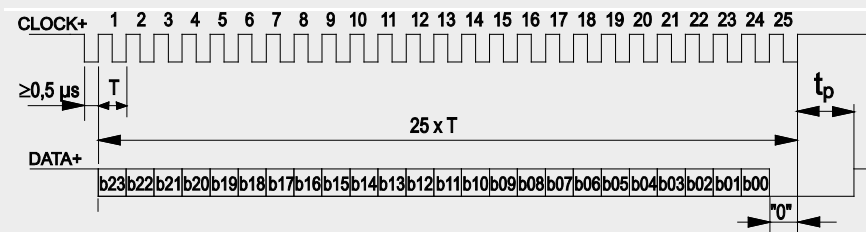
<b>SSI</b> Synchronous serial interface SSI 	Interface	EIA RS-422
	Excitation voltage	10 ... 36 V DC, residual ripple 10 mV <sub>ss</sub>
	Excitation current	typical 22 mA at 24 V DC typical 46 mA at 12 V DC 150 mA max.
	Clock frequency	100 kHz ... 1 MHz
	Code	Gray-Code, Dual-Code
	Delay between pulse trains (t <sub>p</sub> )	>25 μs
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Operating temperature	-40 ... +85°C
	EMC	DIN EN 61326-1:2013

### Description

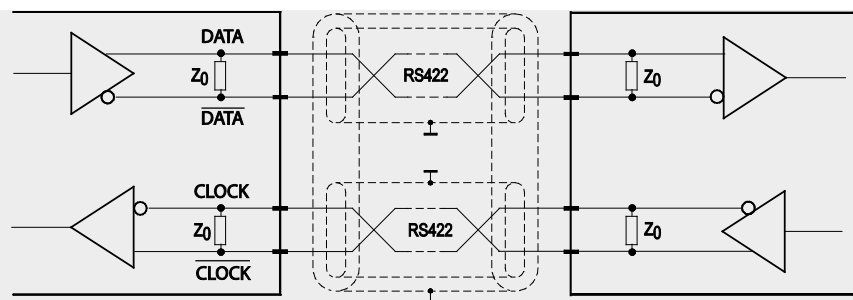
The data transmission takes place by means of the two signals CLOCK and DATA. The processing unit (PLC, microcomputer) sends pulse sequences which clock the data transmission at the required transfer rate. With the first falling edge of the pulse sequence the position of the sensor is recorded and stored. The following rising edges control the bit-by-bit transfer of the data word. After a delay time the next new position information can be transmitted.

### Data format

(Train of 26 pulses)



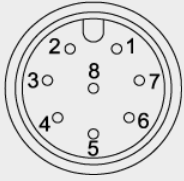
### Recommended processing circuit



### Transmission rate

Cable length	Baud rate	Note:
50 m	100-400 kHz	Extension of the cable length will reduce the maximum transmission rate.  The signals $\overline{\text{CLOCK}}$ and $\overline{\text{DATA}}$ must be connected in a twisted pair cable, shielded in pairs, the pairs also commonly shielded.
100 m	100-300 kHz	



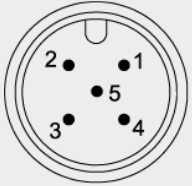
Signal wiring	Signal	Connector pin no.	Cable color
<b>Connector M12, 8 pin</b>  View to the sensor connector	Excitation +	1	white
	Excitation GND	2	brown
	CLOCK	3	green
	$\overline{\text{CLOCK}}$	4	yellow
	DATA	5	grey
	$\overline{\text{DATA}}$	6	pink
	-	7	blue
	-	8	red

## Description


CANopen interface with process data for position and cam functions, programmable are preset, resolution, filtering and cam switching points.

<b>CANOP</b> <b>CANOP/R</b> CANopen 	CAN specification	ISO 11898, Basic and Full CAN 2.0 B
	Communication profile	CANopen CiA 301 V 4.02, Slave
	Encoder profile	Encoder CiA 406 V 3.2
	Error Control	Node Guarding, Heartbeat, Emergency Message
	Node ID	Adjustable via LSS or via object dictionary
	PDO	4 TxPDO, 0 RxPDO, no linking, static mapping
	PDO Modes	Event-/Time triggered, Remote-request, Sync cyclic/acyclic
	SDO	1 Server, 0 Client
	CAM	8 cams
	Certified	yes
	Transmission rate	50 kBit to 1 MBit, adjustable via LSS or via object dictionary
	Nodes	127 max.
	Bus-Anschluss	M12 connector, 5 pin
	Integrated bus terminating resistor (optional)	120 Ω
	Bus, galvanic isolated	no

<b>Specifications</b>	Excitation voltage	18 ... 36 V DC 11 ... 36 V DC for measurement length <1m
	Excitation current	typical 20 mA at 24 V DC typical 40 mA at 12 V DC max. 80 mA
	Number of position magnets	1 ... 4
	Resolution	50 μm
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> / °C f.s.
	Repeatability	1 LSB
	Operating temperature	-40 ... +85 °C
	Protection	Reverse polarity, short circuit
	Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
	EMC	DIN EN 61326-1:2013

Signal wiring	Output signals	Connector pin no.
<b>Connector M12, 5 pin</b>  View to the sensor connector	Shield	1
	Excitation +	2
	GND	3
	CAN-H	4
	CAN-L	5

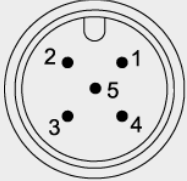
When using multiple magnets, the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

<b>CANJ1939</b> <b>CANJ1939/R</b> SAE J1939 	CAN Specification	ISO 11898, Basic and Full CAN 2.0 B
	Transceiver	24V-compliant, not isolated
	Communication profile	SAE J1939
	Baud Rate	250 kbit/s
	Internal termination resistor (optional)	120 Ω
	Address	Default 247d, configurable

<b>NAME Fields</b>	Arbitrary address capable	1	no
	Industry group	0	Global
	Vehicle system	7Fh (127d)	Non specific
	Vehicle system instance	0	
	Function	FFh (255d)	Non specific
	Function instance	0	
	ECU instance	0	
	Manufacturer	145h (325d)	Manufacturer ID
	Identity number	0nnn	Serial number 21 bit

<b>Parameter Group Numbers (PGN)</b>	Configuration data	PGN EF00h	Proprietary-A (PDU1 peer-to-peer)
	Process data	PGN FFnnh	Proprietary-B (PDU2 broadcast); nn Group Extension (PS) configurable

<b>Specifications</b>	Excitation voltage	18 ... 36 V DC 11 ... 36 V DC for measurement length <1m
	Excitation current	20 mA typical at 24 V DC 40 mA typical at 12 V DC, max. 80 mA
	Measuring rate	1 kHz (asynchronous)
	Stability (temperature)	±50 x 10 <sup>-6</sup> /°C f.s. (typical)
	Repeatability	1 LSB
	Operating temperature	-40 ... 85°C
	Protection	Reverse polarity, short circuit
	Dielectric strength	500 V (V AC, 50 Hz, 1 min.)
	EMV	DIN EN 61326-1:2013

Signal wiring	Output signals	Connector pin no.
<b>Connector M12, 5 pin</b>  View to the sensor connector	Shield	1
	Excitation +	2
	GND	3
	CAN-H	4
	CAN-L	5

When using multiple magnets, the distance between two magnets must be min. 70 mm to identify the single magnets definitely.

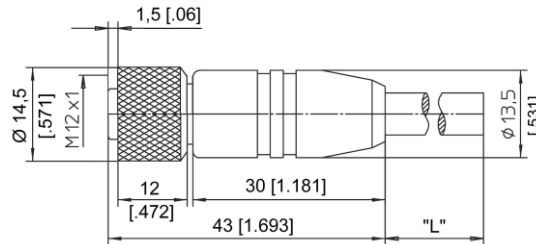
## Connector cables

### Connector/bus cable M12, 5 pin CAN-Bus

The 5-lead shielded cable is supplied with a female 5 pin M12 connector at one end and a male 5 pin M12 connector at the other end.

Available lengths are 0.3 m, 2 m, 5 and 10 m.

Cable diameter: 6.7 ±0.2 mm



#### Order code

**KAB - xM - M12/5F/G - M12/5M/G - CAN**

IP69: **KAB - xM - M12/5F/G/69K - M12/5M/G/69K - CAN**

xM = length in m

### T-connector for bus cable M12, 5 pin CAN-Bus

#### Order code

**KAB - TCONN - M12/5M - 2M12/5F - CAN**



### Terminating resistor M12, 5 pin CAN-Bus

#### Order code

**KAB - RTERM - M12/5M/G - CAN**



#### Applicable for cable carriers

Maximum movement speed	3 m/s
Maximum acceleration	5 m/s <sup>2</sup>
Minimum bending radius	10 x cable diameter